```
Characterising
    the set of
(untruncated)
    signature
    Horatio
Boedihardjo
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# Characterising the set of (untruncated) signature 

# Horatio Boedihardjo 

University of Warwick

July 10, 2020

## The starting point...

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Hambly, B. and Lyons, T., 2010. Uniqueness for the signature of a path of bounded variation and the reduced path group. Annals of Mathematics, pp.109-167.

## Paths with concatenation

| Characterising <br> the set of <br> (untruncated) <br> signature | Definition (Paths) |
| :---: | :--- |
| Horatio | The set of paths: |
| Boedihardjo | $P=\left\{x:[0,1] \rightarrow \mathbb{R}^{d}: x\right.$ continuous, $\left.x(0)=0\right\}$. |

## Paths with concatenation

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## Definition (Paths)

The set of paths:

$$
P=\left\{x:[0,1] \rightarrow \mathbb{R}^{d}: x \text { continuous, } x(0)=0\right\}
$$

## Definition (Concatenation)

Given $x, y \in P$, define

$$
(x y)(t)= \begin{cases}x(2 t), & t \in\left[0, \frac{1}{2}\right] \\ x(1)+y(2 t-1), & t \in\left[\frac{1}{2}, 1\right]\end{cases}
$$

## Paths with concatenation

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## Definition (Paths)

The set of paths:

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$$

## Goal:

Turn $(P$,$) into a group.$

## Definition of a group

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## Definition

Recall $(G, *)$ is a group if

1. (Closure)

$$
x * y \in G \quad \forall x, y \in G
$$

2. (Associativity)

$$
(x * y) * z=x *(y * z), \quad \forall x, y, z \in G
$$

3. (Identity)

$$
\exists e \in G \quad x * e=e * x=x \quad \forall x \in G .
$$

4. (Inverse)

$$
\forall x \in G \quad \exists y \in G \quad x * y=e
$$

No inverse

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## Fact

Path almost never have inverse wrt concatenation. Identity element:

$$
e(t)=0 \forall t \in[0,1]
$$

Candidate for inverse:

$$
\overleftarrow{x}(t)=x(1-t)-x(1)
$$

Then

$$
(x \overleftarrow{x})(t)= \begin{cases}x(2 t), & t \in\left[0, \frac{1}{2}\right] ; \\ x(2-2 t), & t \in\left[\frac{1}{2}, 1\right] .\end{cases}
$$

Unless $x=e$,

$$
x \overleftarrow{x} \neq e
$$

## No inverse

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Need an equivalence relation $\sim$ on $P$ such that: 1

$$
x \overleftarrow{x} \sim \overleftarrow{x} x \sim e
$$

All of the followings are $\sim e$ :


## No inverse

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Need an equivalence relation $\sim$ on $P$ such that: 1

$$
x \overleftarrow{x} \sim \overleftarrow{x} x \sim e
$$

2

$$
x_{1} \sim x_{2}, y_{1} \sim y_{2} \Longrightarrow x_{1} y_{1} \sim x_{2} y_{2}
$$

All of the followings are $\sim e$ :


## Tree-like path

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## Definition ( $\mathbb{R}$-tree, Favre-Jonsson04)

If $\tau$ is a partially ordered set satisfying:

1. $\tau$ has global min. (call $r$ ) and pairwise min.
2. For any $t \in \tau$, the set below is totally ordered

$$
\{s \in \tau: s \preceq t\} ;
$$

3. $\exists L: \tau \rightarrow \mathbb{R}_{\geq 0}$ map intervals in $\tau$ bijectively to intervals in $\mathbb{R}$.

If $d(s, t)=L(t)+L(s)-2 L(s \wedge t)$,
then $(\tau, d)$ is a $\mathbb{R}$-tree.
$b$

## Tree-like path

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Definition (Loop in a tree)
Let $\tau$ be a $\mathbb{R}$-tree. A loop in $\tau$ is a continuous function $\phi:[0,1] \rightarrow \tau$ such that $\phi(0)=\phi(1)$.

## Tree-like path

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Definition (Loop in a tree)
Let $\tau$ be a $\mathbb{R}$-tree. A loop in $\tau$ is a continuous function
$\phi:[0,1] \rightarrow \tau$ such that $\phi(0)=\phi(1)$.


## Definition (Tree-like Hambly-Lyons10)

A path $x:[0,1] \rightarrow V$ is tree-like if there exists:

1. a loop $\phi$ in a $\mathbb{R}$-tree $\tau$;
2. a continuous function $\psi: \tau \rightarrow V$

$$
x=\psi \circ \phi
$$

## Tree-like equivalence

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Definition (Tree-like relation, Hambly-Lyons10)
We define a relation $\sim$ on paths by $x_{1} \sim x_{2}$ if

$$
x_{1} \overleftarrow{x_{2}} \quad \text { is a tree-like path. }
$$

## Tree-like equivalence

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$$
x_{1} \overleftarrow{x_{2}} \quad \text { is a tree-like path. }
$$

## Theorem (Hambly-Lyons10)

The relation $\sim$ is an equivalence relation on the set of bounded variation paths.
The set

$$
R P=\left\{[x]_{\sim}: x:[0,1] \rightarrow \mathbb{R}^{d} \text { continuous, } B V, x(0)=0\right\}
$$

is called the (BV) Reduced path group.

## Proof of Tree-like equivalence 1

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## Definition (Signature)

The signature of $x:[0,1] \rightarrow \mathbb{R}^{d}$ is defined by
$S(x)_{0,1}=1+\int_{0}^{1} \mathrm{~d} x_{t_{1}}+\ldots+\int_{0<t_{1}<\ldots<t_{n}<1} \mathrm{~d} x_{t_{1}} \otimes \ldots \otimes \mathrm{~d} x_{t_{n}}+\ldots$.

## Proof of Tree-like equivalence 1

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$$

## Theorem (Hambly-Lyons10)

If $x$ has bounded variation (BV),

$$
S(x)_{0,1}=1 \Longleftrightarrow x \text { is tree-like. }
$$

## Proof of Tree-like equivalence 1

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$$

## Theorem (Hambly-Lyons10)

If $x$ has bounded variation (BV),

$$
S(x)_{0,1}=1 \Longleftrightarrow x \text { is tree-like. }
$$

## Corollary

$x_{1} \sim x_{2} \Longleftrightarrow S\left(x_{1}\right)_{0,1}=S\left(x_{2}\right)_{0,1}$ for $B V$ paths.

## Reduced paths

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Definition (Reduced paths)
A path $x:[0,1] \rightarrow \mathbb{R}^{d}$ is reduced if

$$
\text { length }(x)=\inf \left\{\operatorname{length}(\alpha): S(\alpha)_{0,1}=S(x)_{0,1}\right\} .
$$

## Reduced paths

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## Definition (Reduced paths)

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$$
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$$

## Corollary (Hambly-Lyons10)

If $x_{1}, x_{2}$ are reduced paths with bounded variation,
$S\left(x_{1}\right)_{0,1}=S\left(x_{2}\right)_{0,1} \Longleftrightarrow x_{1}=x_{2}$ up to translation, reparam.

## Proof of uniqueness

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## Definition

Let $\operatorname{Sh}(n, k)$ be the set of bijections $\sigma:\{1, \ldots, n+k\} \rightarrow\{1, \ldots, n+k\}$ such that

$$
\begin{aligned}
& \sigma(1)<\sigma(2)<\ldots<\sigma(n) \\
& \sigma(n+1)<\ldots<\sigma(n+k) .
\end{aligned}
$$

## Proof of uniqueness

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## Definition

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$$
\begin{aligned}
& \sigma(1)<\sigma(2)<\ldots<\sigma(n) \\
& \sigma(n+1)<\ldots<\sigma(n+k) .
\end{aligned}
$$

Lemma ("Shuffle product formula")

$$
\begin{aligned}
& \text { If } x=\left(x^{1}, \ldots, x^{d}\right), \\
& \\
& =\int_{0<t_{1}<\ldots<t_{n}<t} \mathrm{~d} x_{t_{1}}^{i_{1}} \ldots \mathrm{~d} x_{t_{n}}^{i_{n}} \cdot \int_{0<t_{1}<\ldots<t_{k}<t} \int_{0<t_{1}(n, k)} \int_{0<t_{1}<\ldots<t_{n+k}<t}^{i_{n+1}} \ldots \mathrm{~d} x_{t_{k}}^{i_{n+k}} \\
& \mathrm{~d} x_{t_{1}}^{i_{\sigma}-1(1)} \ldots \mathrm{d} x_{t_{n+k}}^{i_{\sigma-1}(n+k)} .
\end{aligned}
$$

## Linear functionals on signatures

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## Examples

## Closure under products

$$
\begin{aligned}
& \left(\int_{0<t_{1}<t_{2}<t} \mathrm{~d} x_{t_{1}}^{1} \mathrm{~d} x_{t_{2}}^{2}\right)\left(\int_{0<t_{1}<t} \mathrm{~d} x_{t_{1}}^{1}\right) \\
= & 2 \int_{0<t_{1}<t_{2}<t_{3}<t} \mathrm{~d} x_{t_{1}}^{1} \mathrm{~d} x_{t_{2}}^{1} \mathrm{~d} x_{t_{3}}^{2}+\int_{0<t_{1}<t_{2}<t_{3}<t} \mathrm{~d} x_{t_{1}}^{1} \mathrm{~d} x_{t_{2}}^{2} \mathrm{~d} x_{t_{3}}^{1} .
\end{aligned}
$$

Closure under integration

$$
\begin{aligned}
& \int_{0}^{t}\left(\int_{0<t_{1}<t_{2}<u} \mathrm{~d} x_{t_{1}}^{1} \mathrm{~d} x_{t_{2}}^{2}+\int_{0<t_{1}<u} \mathrm{~d} x_{t_{1}}^{1}\right) \mathrm{d} x_{u}^{2} \\
= & \int_{0<t_{1}<t_{2}<t_{3}<u} \mathrm{~d} x_{t_{1}}^{1} \mathrm{~d} x_{t_{2}}^{2} \mathrm{~d} x_{t_{3}}^{2}+\int_{0<t_{1}<t_{2}<u} \mathrm{~d} x_{t_{1}}^{1} \mathrm{~d} x_{t_{2}}^{2} .
\end{aligned}
$$

## Proof

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Lemma (B. Geng Lyons Yang 16)
If $t \rightarrow S(x)_{0, t}$ and $t \rightarrow S(y)_{0, t}$ both injective.
If $x$ not reparametrisation of $y$, then
$\exists$ smooth functions $L_{1}, L_{2}$

$$
\int_{0}^{1} L_{1}\left(S(x)_{0, u}\right) \mathrm{d} L_{2}\left(S(x)_{0, u}\right) \neq \int_{0}^{1} L_{1}\left(S(y)_{0, u}\right) \mathrm{d} L_{2}\left(S(y)_{0, u}\right.
$$

## Proof

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$$

## Corollary

If $t \rightarrow S(x)_{0, t}$ and $t \rightarrow S(y)_{0, t}$ injective, then

$$
S(x)_{0,1}=S(y)_{0,1} \Longleftrightarrow x \quad \text { reparametrisation of } y .
$$

## Isometry

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Theorem (Hambly-Lyons isometry)
A path $x:[0,1] \rightarrow \mathbb{R}^{d}$ satisfies $\left\|x_{t}^{\prime}\right\|=1 \forall t$ and is $C^{3}$, then

$$
\begin{equation*}
\text { length }(x)=\limsup _{n \rightarrow \infty}\left\|n!\int_{0<t_{1}<\ldots<t_{n}<1} \mathrm{~d} x_{t_{1}} \otimes \ldots \otimes \mathrm{~d} x_{t_{n}}\right\|^{\frac{1}{n}} \tag{1}
\end{equation*}
$$

where $\|\cdot\|$ is the projective norm w.r.t. Euclidean norm.

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\end{equation*}
$$

where $\|\cdot\|$ is the projective norm w.r.t. Euclidean norm.

## Open problem

1. Is limsup in (1) in fact a lim?
2.Extend isometry (1) to reduced bounded variation paths.

## $\lim =\lim \sup$

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Theorem (B.-Geng)
If $x$ is a non tree-like, B.V. path, then there is at most finitely many $n$ such that

$$
\int_{0<t_{1}<\ldots<t_{n}<1} \mathrm{~d} x_{t_{1}} \otimes \ldots \otimes \mathrm{~d} x_{t_{n}}=0 .
$$

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\int_{0<t_{1}<\ldots<t_{n}<1} \mathrm{~d} x_{t_{1}} \otimes \ldots \otimes \mathrm{~d} x_{t_{n}}=0
$$

## Theorem (Chang-Lyons-Ni)

If $x$ is a B.V. path, then the following limit exists:

$$
\lim _{n \rightarrow \infty}\left\|n!\int_{0<t_{1}<\ldots<t_{n}<1} \mathrm{~d} x_{t_{1}} \otimes \ldots \otimes \mathrm{~d} x_{t_{n}}\right\|^{\frac{1}{n}}
$$

## $\lim =\lim \sup$

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## Ideas from Chang-Lyons-Ni.

$$
\begin{aligned}
& \text { If } x=\left(x^{1}, \ldots, x^{d}\right), \\
& \\
& =\int_{0<t_{1}<\ldots<t_{n}<t} \mathrm{~d} x_{t_{1}}^{i_{1}} \ldots \mathrm{~d} x_{t_{n}}^{i_{n}} \cdot \int_{0<t_{1}<\ldots<t_{k}<t} \int_{0<t_{1}(n, k)} \int_{0<t_{1}<\ldots<t_{n+k}<t}^{i_{n+1}} \ldots \mathrm{~d} x_{t_{k}}^{i_{n+k}} \\
& \mathrm{~d} x_{t_{1} i^{-1}(1)}^{i_{n}} \ldots \mathrm{~d} x_{t_{n+k}{ }^{i^{-1}(n+k)}} .
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
& \left|\int_{0<t_{1}<\ldots<t_{n}<t} \mathrm{~d} x_{t_{1}}^{i_{1}} \ldots \mathrm{~d} x_{t_{n}}^{i_{n}}\right| \cdot\left|\int_{0<t_{1}<\ldots<t_{k}<t} \mathrm{~d} x_{t_{1}}^{i_{n+1}} \ldots \mathrm{~d} x_{t_{k}}^{i_{n+k}}\right| \\
\leq & |S h(n, k)| \max _{\sigma \in S h(n, k)}\left|\int_{0<t_{1}<\ldots<t_{n+k}<t} \mathrm{~d} x_{t_{1}}^{i_{\sigma-1}(1)} \ldots \mathrm{d} x_{t_{n+k}}^{i_{\sigma-1}(n+k)}\right| .
\end{aligned}
$$

## Proof of isometry (special case)

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Lemma (Hambly-Lyons10)
Let $Y_{t}^{\lambda}$ be the solution to

$$
\mathrm{d} Y_{t}^{\lambda}=\lambda A\left(\mathrm{~d} x_{t}\right) Y_{t}^{\lambda}, \quad Y_{0}^{\lambda}=v
$$

with $\|v\|=1$. If $\|A\|_{\mathbb{R}^{d} \rightarrow L\left(\mathbb{R}^{n}, \mathbb{R}^{n}\right)}=1$, then
$\limsup _{\lambda \rightarrow \infty} \frac{\log \left\|Y_{1}^{\lambda}\right\|}{\lambda} \leq \lim _{n \rightarrow \infty}\left\|n!\int_{0<t_{1}<\ldots<t_{n}<1} \mathrm{~d} x_{t_{1}} \otimes \ldots \otimes \mathrm{~d} x_{t_{n}}\right\|^{\frac{1}{n}}$.

## Proof of isometry (special case)

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## Lemma (Hambly-Lyons10)

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$$
Y_{1}^{\lambda}=v+\ldots+\lambda^{n} \int_{0<t_{1}<\ldots<t_{n}<1} A \mathrm{~d} x_{t_{1}} \ldots A \mathrm{~d} x_{t_{n}} v \ldots
$$

## Isometry

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Theorem (Lyons-Xu16)
If $\left\|x^{\prime}\right\|=1$ and $x$ is $C^{1}$, then
$\limsup _{n \rightarrow \infty}\left\|n!\int_{0<t_{1}<\ldots<t_{n}<1} \mathrm{~d} x_{t_{1}} \otimes \ldots \otimes \mathrm{~d} x_{t_{n}}\right\|^{\frac{1}{n}}=$ length $(x)$.
(2)

## Isometry

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## Theorem (Lyons-Xu16)

If $\left\|x^{\prime}\right\|=1$ and $x$ is $C^{1}$, then
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Theorem (B.-Geng To Appear)
If $d=2,\left\|x^{\prime}\right\|=1$ and
$\forall t \in[0,1], \exists \delta, a$, s.t $\operatorname{Arg}\left(x_{s}^{\prime}\right) \in(a, a+\pi-\varepsilon) \forall s \in(t-\delta, t+\delta)$
, then (2) holds.

## Isometry (rough path case)

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## Theorem (B.-Geng19)

If $B$ is multi-dimensional Brownian motion, there exists deterministic $C>0$, almost surely,

$$
\begin{equation*}
\limsup _{n \rightarrow \infty}\left\|\left(\frac{n}{2}\right)!\int_{0<t_{1}<\ldots<t_{n}<t} \mathrm{~d} B_{t_{1}} \otimes \ldots \otimes \mathrm{~d} B_{t_{n}}\right\|^{\frac{2}{n}}=C t . \tag{3}
\end{equation*}
$$

## Isometry (rough path case)

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\end{equation*}
$$

## Theorem (B.-Geng-Souris20)

If $x_{t}=e^{t\left(\mathcal{P}_{1}+\ldots+\mathcal{P}_{M}\right)}$, where $\mathcal{P}_{i}$ is Lie polynomial of degree $i$, there exists $C>0$ depending on $M, d$,

$$
\begin{aligned}
C\left\|\mathcal{P}_{M}\right\| & \leq \limsup _{n \rightarrow \infty}\left\|\left(\frac{n}{M}\right)!\int_{0<t_{1}<\ldots<t_{n}<t} \mathrm{~d} x_{t_{1}} \otimes \ldots \otimes \mathrm{~d} x_{t_{n}}\right\|^{\frac{M}{n}} \\
& \leq\left\|\mathcal{P}_{M}\right\| .
\end{aligned}
$$

## Image of signature

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## Open problem

How to characterise

$$
\left\{S(x)_{0,1}: x:[0,1] \rightarrow \mathbb{R}^{d}, \text { continuous, } \mathrm{BV}\right\}
$$

as a subset of tensor algebra?

## Image of signature

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How to characterise

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$$

as a subset of tensor algebra?

## Lemma (Chen)

Define $L_{1}=\mathbb{R}^{d}$ and if $[a, b]=a \otimes b-b \otimes a$,

$$
L_{n+1}=\operatorname{span}\left\{[a, b]: a \in \mathbb{R}^{d}, b \in L_{n}\right\} .
$$

Then

$$
\log S(x)_{0,1} \in \Pi_{n=1}^{\infty} L_{n}
$$

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## Lyons-Sidorova conjecture (modified)

If $x$ has bounded variation and

$$
\log S(x)_{0,1}=\sum_{n=1}^{\infty} I_{n}
$$

where $I_{n} \in L_{n}$, then $\exists \lambda$ such that

$$
\sum_{n=1}^{\infty} \lambda^{n}\left\|I_{n}\right\|=\infty
$$

unless $x$ is conjugate and tree-like equivalent to a straight line.

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Lemma (Key Ingredient of Lyons-Sidorova)
Lyons-Sidorova conjecture is true for the path $(x, y)$ if there exists $\lambda$ such that if

$$
\mathrm{d} Y_{t}^{\lambda}=\lambda\left(\begin{array}{cc}
\mathrm{d} x_{t} & \mathrm{~d} y_{t} \\
\mathrm{~d} y_{t} & -\mathrm{d} x_{t}
\end{array}\right) Y_{t}^{\lambda}, \quad Y_{t}^{\lambda}=I
$$

then $Y_{1}^{\lambda} \notin \exp \left(s l\left(2 ; \mathbb{R}^{2}\right)\right)$.

## Hambly-Lyons open problems on signatures

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Problem 1.10: Uniqueness problem
Problem 1.11: Inversion problem
Problem 1.12: Image problem.

